

Monotone Iterative Techniques for Discontinuous Functional Impulsive Equations

Alberto Cabada, Jan Tomeček

Preliminaries

Carathéodory Case Considered Problem Definitions and Hypotheses Existence Results Extremal Solutions

Discontinuous Case

# Monotone Iterative Techniques for Discontinuous Functional Impulsive Equations

## Alberto Cabada and Jan Tomeček

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Spain

Department of Mathematics Palacký University

CZECH REPUBLIC

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# Preliminaries *p* – Laplacian Equations

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Discontinuous Case

$$\frac{d}{dt}\phi_p(u'(t)) = \frac{d}{dt}(|u'(t)|^{p-2}u'(t)) = f(t, u(t), u'(t)), \ t \in [0, T].$$

for some p > 1.



# Preliminaries $\phi$ – Laplacian Equations

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$$\frac{d}{dt}\phi(u'(t))=f(t,u(t),u'(t)),\ t\in[0,T].$$

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$$\frac{d}{dt}\phi(u'(t))=f(t,u(t),u'(t)),\ t\in[0,T].$$

where  $\phi$  is an increasing homeomorphism from  $\mathbb{R}$  onto  $\mathbb{R}$ .



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C. Bereanu, G. Bojnár, J. A. Cid, C. De Coster, P. Drabek, M. García – Huidobro, P. Habets, P. Jebelean, A. Lomtatidze, R. López-Pouso, R. Manásevich, C. Marcelli, J. Mawhin, F. Minhós, D. O'Regan, V. Polášek I. Rachunková, F. Sadyrbaev, S. Staněk, J. Tomeček, M. Tvrdý, I. Yermachenko, F. Zanolin.



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Discontinuous Case This kind of problems study physical phenomena in which the solutions of the considered problems present an immediate change on its conditions. Such process induces jumps in the value of the function or in its derivatives.



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• V. Lakshmikantham, D. D. Bainov, P. S. Simeonov, *Theory of impulsive differential equations*. World Scientific, Singapore, 1989.



## Preliminaries Lower and Upper Solutions

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## Preliminaries

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Discontinuous Case This method allow us to ensure the existence of a solution of the considered problem lying between the lower and the upper solutions, i. e., we have information about the existence and location of the solutions.



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 A. Cabada, J. Tomeček, Existence of extremal solutions for nonlinear discontinuous impulsive functional φ-Laplacian equations with nonlinear discontinuous functional boundary conditionss, *Mem. Differential Equations Math. Phys.* **40**, (2007), 1 – 16.



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Discontinuous Case Let  $p \in \mathbb{N}$  be fixed, and  $P = \{t_1, \ldots, t_p\}$ ,



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Discontinuous Case

Let 
$$p \in \mathbb{N}$$
 be fixed, and  $P = \{t_1, \ldots, t_p\}$ , with

$$0 = t_0 < t_1 < \dots < t_p < t_{p+1} = T$$

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 be fixed, and  $P = \{t_1, \ldots, t_p\}$ , with

$$0 = t_0 < t_1 < \cdots < t_p < t_{p+1} = T$$

We study the nonlinear impulsive boundary value problem  $(P_1)$ 

$$(\phi(u'(t)))' = f(t,u(t),u'(t))$$
 for a. e.  $t \in [0,T] ackslash P_{t}$ 



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$$(\phi(u'(t)))' = f(t, u(t), u'(t))$$
 for a. e.  $t \in [0, T] \setminus P$ 

$$g_1(u(0), u(T)) = 0, \\g_2(u(0), u(T), u'(0), u'(T), u) = 0, \end{cases}$$



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We study the nonlinear impulsive boundary value problem  $(P_1)$ 

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$$g_1(u(0), u(T)) = 0, \\g_2(u(0), u(T), u'(0), u'(T), u) = 0, \end{cases}$$

$$\left. \begin{array}{c} I_k(u(t_k), u(t_k^+)) = 0, \\ M_k(u(t_k), u(t_k^+), u'(t_k), u'(t_k^+), u) = 0, \end{array} \right\} \text{for } k = 1, \dots, p.$$

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### Considered Problem

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Discontinuous Case

## These boundary conditions include Dirichlet conditions

$$g_1(x, y) = x,$$
  $g_2(x, y, z, w, u) = y$ 



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Discontinuous Case These boundary conditions include Dirichlet conditions

$$g_1(x,y) = x,$$
  $g_2(x,y,z,w,u) = y$ 

as well as the periodic ones

$$g_1(x,y) = y - x,$$
  $g_2(x,y,z,w,u) = z - w$ 

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and a great variety of non local boundary conditions such as



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$$\max_{t\in[0,T]} \{u(t)\} = c, \ u(0) = u(T)$$

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$$g_1(x,y) = y - x,$$
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and a great variety of non local boundary conditions such as

$$\max_{t \in [0,T]} \{u(t)\} = c, \ u(0) = u(T)$$
$$\int_0^T u(s) ds = c, \ u(T) = d$$

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It is important to note that by defining



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It is important to note that by defining

$$I_k(x,y) = x - y$$

and

$$M_k(x, y, z, w, u) = w - z$$

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we give existence results for the non impulsive problem.



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Discontinuous Case In order to define the concept of solution we denote

$$J_0 = [0, t_1]$$
 and  $J_k = (t_k, t_{k+1}]$  for all  $k = 1, ..., p$ .

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and define the following sets:

$$\begin{aligned} \mathcal{L}_{P}^{m} &= \{ u : [0, T] \to \mathbb{R} : \text{ for all } k = 0, \dots, p, \, u \in C^{m}(J_{k}), \\ &\text{ there exist } u^{(l)}(t_{k}^{+}), \, k = 1, \dots, p \; u^{(l)}(t_{k}^{-}) \equiv u^{(l)}(t_{k}), \\ &k = 1, \dots, p + 1; \; l = 0, \dots, m \end{aligned}$$

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$$C_P^m = \{ u : [0, T] \to \mathbb{R} : \text{ for all } k = 0, \dots, p, u \in C^m(J_k), \\ \text{there exist } u^{(l)}(t_k^+), \ k = 1, \dots, p \ u^{(l)}(t_k^-) \equiv u^{(l)}(t_k), \\ k = 1, \dots, p+1; \ l = 0, \dots, m \}$$

## and

f

$$W^{m,q}_P=\{u:[0,T] o\mathbb{R}\ :\ u_{|J_k}\in W^{m,q}(J_k), k=0,\ldots,p\}$$
 or  $m\in\mathbb{N}\cup\{0\}$  and  $1\leq q\leq\infty.$ 



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Discontinuou: Case Definition A function  $\alpha \in W_P^{1,\infty}$  is called a lower solution of the problem  $(P_1)$  if for each  $t_0 \in (0, T) \setminus P$  either



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 $D_{-}\alpha(t_0) < D^{+}\alpha(t_0)$ 



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$$D_{-}\alpha(t_0) < D^{+}\alpha(t_0)$$

or there exists an open interval  $I_0 \subset (0, T) \setminus P$  such that  $t_0 \in I_0$ ,  $\phi \circ \alpha' \in W^{1,1}(I_0)$  and



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or there exists an open interval  $I_0 \subset (0, T) \setminus P$  such that  $t_0 \in I_0$ ,  $\phi \circ \alpha' \in W^{1,1}(I_0)$  and

 $(\phi(lpha'(t)))' \ge f(t, lpha(t), lpha'(t))$  for a. e.  $t \in I_0$ .



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Discontinuous Case For all k = 1, ..., p, functions  $I_k(\alpha(t_k), \cdot)$  are one-to-one and there exist  $\alpha'(t_k^-)$  and  $\alpha'(t_k^+)$  satisfying



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 $I_k(\alpha(t_k), \alpha(t_k^+)) = 0 \le M_k(\alpha(t_k), \alpha(t_k^+), \alpha'(t_k^-), \alpha'(t_k^+), \alpha).$ 



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$$_{k}(\alpha(t_{k}),\alpha(t_{k}^{+}))=0\leq M_{k}(\alpha(t_{k}),\alpha(t_{k}^{+}),\alpha'(t_{k}^{-}),\alpha'(t_{k}^{+}),\alpha).$$

Moreover,  $g_1(\cdot, \alpha(T))$  is one-to-one and there exist  $\alpha'(0^+)$ and  $\alpha'(T^-)$  satisfying


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Moreover,  $g_1(\cdot, \alpha(T))$  is one-to-one and there exist  $\alpha'(0^+)$ and  $\alpha'(T^-)$  satisfying

 $g_1(\alpha(0),\alpha(T)) = 0 \leq g_2(\alpha(0),\alpha(T),\alpha'(0^+),\alpha'(T^-),\alpha).$ 



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Discontinuou: Case

 $(H_1)$   $f \in Car([0, T] \times \mathbb{R}^2).$ 



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Discontinuou: Case  $(H_1)$   $f \in Car([0, T] \times \mathbb{R}^2).$ 

(*H*<sub>2</sub>)  $I_k \in C^0(\mathbb{R}^2)$  and  $M_k \in C^0(\mathbb{R}^4 \times C_P^1)$  satisfy some suitable monotonicity properties



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Discontinuou Case

# $(H_1) f \in Car([0, T] \times \mathbb{R}^2).$

 $(H_2)$   $I_k \in C^0(\mathbb{R}^2)$  and  $M_k \in C^0(\mathbb{R}^4 \times C_P^1)$  satisfy some suitable monotonicity properties

 $(H_3)$   $g_1 \in C^0(\mathbb{R}^2)$  and  $g_2 \in C^0(\mathbb{R}^4 \times C_P^1)$  satisfy some suitable monotonicity properties



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Discontinuous Case  $(H_1)$   $f \in Car([0, T] \times \mathbb{R}^2).$ 

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 $(H_4) \phi : \mathbb{R} \to \mathbb{R}$  is a continuous and strictly increasing function.



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(*H*<sub>5</sub>) There exist  $\alpha \leq \beta$  lower and upper solutions of (*P*<sub>1</sub>)



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 $(H_2)$   $I_k \in C^0(\mathbb{R}^2)$  and  $M_k \in C^0(\mathbb{R}^4 \times C_P^1)$  satisfy some suitable monotonicity properties

 $(H_3)$   $g_1 \in C^0(\mathbb{R}^2)$  and  $g_2 \in C^0(\mathbb{R}^4 \times C_P^1)$  satisfy some suitable monotonicity properties

 $(H_4) \phi : \mathbb{R} \to \mathbb{R}$  is a continuous and strictly increasing function.

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(*H*<sub>5</sub>) There exist  $\alpha \leq \beta$  lower and upper solutions of (*P*<sub>1</sub>)

 $(H_6)$  f satisfies a suitable Nagumo's condition.



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#### Theorem 1 Assume that hypotheses $(H_1) - (H_6)$ hold.



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Discontinuou: Case Theorem 1 Assume that hypotheses  $(H_1) - (H_6)$  hold.

Then there exists at least one solution  $u \in [\alpha, \beta]$  of the problem  $(P_1)$ 

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Discontinuous Case Lemma 1 Let  $\tilde{f} \in L^1[0, T]$  and  $A_k$ ,  $B_k \in \mathbb{R}$ ,  $k = 0, \dots, p$ .



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Lemma 1 Let  $\tilde{f} \in L^1[0, T]$  and  $A_k$ ,  $B_k \in \mathbb{R}$ , k = 0, ..., p. Suposse that  $\bar{\phi} : \mathbb{R} \to \mathbb{R}$  is a strictly increasing function that satisfies  $\bar{\phi}(\mathbb{R}) = \mathbb{R}$ .

Then the non homogeneous impulsive Dirichlet problem



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Then the non homogeneous impulsive Dirichlet problem

$$\begin{cases} (\bar{\phi}(u'(t)))' &= \tilde{f}(t), \text{ a. e. } t \in [0, T] \setminus P, \\ u(t_k) &= B_{k-1}, k = 1, \dots, p, \\ u(t_k^+) &= A_k k = 1, \dots, p, \\ u(0) &= A_0, \\ u(T) &= B_p, \end{cases}$$



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has a unique solution  $u \in C_P^1$ , such that  $\phi \circ u' \in W_P^{1,1}$ .



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For each  $t \in J_k$ , k = 0, ..., p, the expression of u(t) is given by



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Discontinuou Case For each  $t \in J_k$ , k = 0, ..., p, the expression of u(t) is given by

$$u(t) = A_k + \int_{t_k}^t \overline{\phi}^{-1} \left( \int_{t_k}^z \widetilde{f}(s) ds + \tau_k \right) dz.$$



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$$u(t) = A_k + \int_{t_k}^t \bar{\phi}^{-1} \left( \int_{t_k}^z \tilde{f}(s) ds + \tau_k \right) dz.$$

Here, for each  $k = 0, ..., p, \tau_k$  is the unique solution of the equation

$$B_k - A_k = \int_{t_k}^{t_{k+1}} \overline{\phi}^{-1} \left( \int_{t_k}^z \widetilde{f}(s) ds + \tau \right) dz.$$

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#### Defining

 $\gamma(t, u) = \min\{\beta(t), \max\{u, \alpha(t)\}\} \quad t \in [0, T] \text{ and } u \in \mathbb{R},$ 



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## Lemma 2 Given $v, v_n \in C_P^1$ such that $v_n \to v$ in $C_P^1$ , then



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Discontinuous Case Lemma 2 Given  $v, v_n \in C_P^1$  such that  $v_n \to v$  in  $C_P^1$ , then

) 
$$rac{\mathrm{d}}{\mathrm{d}t}\gamma(t, \mathbf{v}(t))$$
 exists for a.e.  $t\in [0, T]ackslash P;$ 



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Discontinuou Case Lemma 2 Given  $v, v_n \in C^1_P$  such that  $v_n \to v$  in  $C^1_P$ , then

(i) 
$$\frac{\mathrm{d}}{\mathrm{d}t}\gamma(t,v(t))$$
 exists for a.e.  $t \in [0,T] \setminus P$ ;  
(ii)  $\frac{\mathrm{d}}{\mathrm{d}t}\gamma(t,v_n(t)) \to \frac{\mathrm{d}}{\mathrm{d}t}\gamma(t,v(t))$  for a.e.  $t \in [0,T] \setminus P$ .



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$$v, v_n \in C^1_P$$
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(i) 
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 M. X. Wang, A. Cabada, J. J. Nieto, Monotone method for nonlinear second order periodic boundary value problems with Carathéodory functions, *Ann. Polon. Math.* 58, (1993), 221 – 235.



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# Proof of Theorem 1

Given K > 0 the Nagumo Constant, we define:

$$x \in \mathbb{R} \longmapsto \bar{\phi}(x) = \begin{cases} x - K + \phi(K), & \text{for } x > K, \\ \phi(x), & \text{for } -K \le x \le K, \\ x + K + \phi(-K), & \text{for } x < -K. \end{cases}$$



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$$PM \begin{cases} (\bar{\phi}(u'(t)))' &= \tilde{f}_u(t), \text{ a. e. } t \in [0, T] \setminus P, \\ u(t_k) &= B_{k-1}(u), \quad k = 1, \dots, p, \\ u(t_k^+) &= A_k(u) \quad k = 1, \dots, p, \\ u(0) &= A_0(u), \\ u(T) &= B_p(u). \end{cases}$$

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$$\tilde{f}_{u}(t) = f(t, \gamma(t, u(t)), \delta_{\mathcal{K}}(\frac{\mathrm{d}}{\mathrm{d}t}(\gamma(t, u(t))))).$$

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$$(PM) \begin{cases} (\bar{\phi}(u'(t)))' &= \tilde{f}_u(t), \text{ a. e. } t \in [0, T] \backslash P, \\ u(t_k) &= B_{k-1}(u), \quad k = 1, \dots, p, \\ u(t_k^+) &= A_k(u) \quad k = 1, \dots, p, \\ u(0) &= A_0(u), \\ u(T) &= B_p(u). \end{cases}$$

$$\begin{split} \tilde{f}_u(t) &= f(t, \gamma(t, u(t)), \delta_{\mathcal{K}}(\frac{\mathrm{d}}{\mathrm{d}t}(\gamma(t, u(t))))).\\ \delta_{\mathcal{K}}(y) &= \min\{\mathcal{K}, \max\{y, -\mathcal{K}\}\} \quad \text{for all } y \in \mathbb{R}. \end{split}$$

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 $B_{k-1}(u) = \gamma(t_k, u(t_k) + M_k(u(t_k), u(t_k^+), u'(t_k), u'(t_k^+), u)).$ 



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 $B_{k-1}(u) = \gamma(t_k, u(t_k) + M_k(u(t_k), u(t_k^+), u'(t_k), u'(t_k^+), u)).$ 

$$\boldsymbol{A}_{\boldsymbol{k}}(\boldsymbol{u}) = \gamma(\boldsymbol{t}_{\boldsymbol{k}}^{+}, \boldsymbol{u}(\boldsymbol{t}_{\boldsymbol{k}}^{+}) + \boldsymbol{I}_{\boldsymbol{k}}(\boldsymbol{u}(\boldsymbol{t}_{\boldsymbol{k}}), \boldsymbol{u}(\boldsymbol{t}_{\boldsymbol{k}}^{+}))),$$



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$$(PM) \begin{cases} (\bar{\phi}(u'(t)))' &= \tilde{f}_u(t), \text{ a. e. } t \in [0, T] \setminus P, \\ u(t_k) &= B_{k-1}(u), \quad k = 1, \dots, p, \\ u(t_k^+) &= A_k(u) \quad k = 1, \dots, p, \\ u(0) &= A_0(u), \\ u(T) &= B_p(u). \end{cases}$$

 $A_0(u) = \gamma(0, u(0) + g_1(u(0), u(T))),$ 



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$$A_0(u) = \gamma(0, u(0) + g_1(u(0), u(T))),$$

$$B_{\rho}(u) = \gamma(T, u(T) + g_2(u(0), u(T), u'(0), u'(T), u)),$$

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## Define the operator $F: C_P^1 \to C_P^1$ by



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Define the operator  $F: C^1_P \to C^1_P$  by

$$(Fu)(t) = A_k(u) + \int_{t_k}^t \bar{\phi}^{-1}\left(\int_{t_k}^z \tilde{f}_u(s) \,\mathrm{d}s + \tau_k(u)\right) \,\mathrm{d}z$$

for each 
$$u \in C^1_P$$
 and  $t \in J_k$ ,  $k = 0, \dots, p$ .



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Discontinuous Case Define the operator  $F: C^1_P o C^1_P$  by

$$(Fu)(t) = A_k(u) + \int_{t_k}^t \bar{\phi}^{-1}\left(\int_{t_k}^z \tilde{f}_u(s) \,\mathrm{d}s + \tau_k(u)\right) \,\mathrm{d}z$$

for each 
$$u \in C^1_P$$
 and  $t \in J_k$ ,  $k = 0, \dots, p$ .

 $\tau_k(u)$  is the unique solution of equation

$$B_k(u) - A_k(u) = \int_{t_k}^{t_{k+1}} \overline{\phi}^{-1}\left(\int_{t_k}^z \widetilde{f}_u(s) \,\mathrm{d}s + \tau_k(u)\right) \,\mathrm{d}z,$$

for each  $k = 0, \ldots, p$ .



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# • Lemma 1 and Lemma 2 imply that operator *F* is well defined.


### Carathéodory Case Existence Results

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Discontinuou Case • Lemma 1 and Lemma 2 imply that operator *F* is well defined.

• The proof holds from comparison results and degree theory.

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# $(H_2^*)$ $(H_2)$ is fulfilled and $I_k$ is one – to – one in the second variable



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# $(H_2^*)$ $(H_2)$ is fulfilled and $I_k$ is one – to – one in the second variable

 $(H_3^*)$   $(H_3)$  holds and  $g_1$  is one – to – one in the first variable

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#### Theorem 2 Assume hypotheses $(H_1)$ , $(H_2^*)$ , $(H_3^*)$ , $(H_4) - (H_6)$ .



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Discontinuous Case Theorem 2 Assume hypotheses  $(H_1)$ ,  $(H_2^*)$ ,  $(H_3^*)$ ,  $(H_4) - (H_6)$ . Then problem  $(P_1)$  has the minimal and the maximal solution lying between  $\alpha$  and  $\beta$ .



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#### Proof.

Let  $S \neq \emptyset$  be the set of all solutions of the problem ( $P_1$ ) lying between  $\alpha$  and  $\beta$ .



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Let  $S \neq \emptyset$  be the set of all solutions of the problem  $(P_1)$  lying between  $\alpha$  and  $\beta$ .

We prove that given  $u_1$ ,  $u_2 \in S$ , then there exist  $u_3$ ,  $u_4 \in S$  such that

 $u_3 \leq u_1 \leq u_4$  and  $u_3 \leq u_2 \leq u_4$ 

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 $u_3 \leq u_1 \leq u_4$  and  $u_3 \leq u_2 \leq u_4$ 

J. A. Cid, On extremal fixed points in Schauder's theorem with applications to differential equations. *Bull. Belg. Math. Soc. Simon Stevin* **11** (2004), 15 – 20.



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#### Extremal Solutions can be obtained for problem $(P_2)$

$$\phi(u'(t)))' = f(t, u, u(t), u'(t))$$
 for a. e.  $t \in [0, T] \setminus P$ ,



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$$(\phi(u'(t)))' = f(t, u, u(t), u'(t))$$
 for a. e.  $t \in [0, T] \setminus P$ ,

$$g_1(u(0), u) = 0, \\g_2(u(T), u) = 0, \end{cases}$$



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Discontinuous Case Extremal Solutions can be obtained for problem  $(P_2)$ 

$$\phi(u'(t)))' = f(t,u,u(t),u'(t))$$
 for a. e.  $t \in [0,T] \setminus P$ ,

$$g_1(u(0), u) = 0, \\g_2(u(T), u) = 0, \end{cases}$$

$$egin{aligned} & I_k(u(t_k), u) = 0, \ & M_k(u(t_k^+), u) = 0, \end{aligned} 
ight\} ext{for } k = 1, \dots, p. \end{aligned}$$



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Discontinuous Case Extremal Solutions can be obtained for problem  $(P_2)$ 

$$\phi(u'(t)))' = f(t, oldsymbol{u}, u(t), u'(t)) \qquad ext{for a. e. } t \in [0, T] ackslash P,$$

$$g_1(u(0), u) = 0, \\g_2(u(T), u) = 0, \end{cases}$$

$$\begin{cases} I_k(u(t_k), u) = 0, \\ M_k(u(t_k^+), u) = 0, \end{cases}$$
for  $k = 1, \dots, p.$ 

In this case f,  $g_1$ ,  $g_2$ ,  $I_k$  and  $M_k$  can be discontinuous on the second variable.

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### Lemma 3 Let $[\alpha, \beta] \subset C^0_P$ and $G : [\alpha, \beta] \to [\alpha, \beta]$ nondecreasing.



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#### Lemma 3 Let $[\alpha, \beta] \subset C^0_P$ and $G : [\alpha, \beta] \to [\alpha, \beta]$ nondecreasing.

Assume that sequence  $\{Gv_n\}$  has a pointwise limit in  $C_P^0$  whenever  $\{v_n\}$  is a monotone sequence in  $[\alpha, \beta]$ .



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Then G has the least fixed point  $u_*$  and the greatest fixed point  $u^*$ .



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S. Heikkilä, V. Lakshmikantham, Monotone Iterative Techniques for Discontinuous Nonlinear Differential Equations, Marcel Dekker, New York, 1994.



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$$\alpha_0 = \alpha$$
 and  $\alpha_{n+1} = G \alpha_n$ 



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$$\alpha_0 = \alpha \quad \text{and} \quad \alpha_{n+1} = G \, \alpha_n \Longrightarrow \{\alpha_n\} \to \alpha^1$$



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$$\alpha_0 = \alpha \quad \text{and} \quad \alpha_{n+1} = G \, \alpha_n \Longrightarrow \{\alpha_n\} \to \alpha^1$$

If 
$$\alpha^1 < {\sf G} \, \alpha^1$$

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$$\alpha_0 = \alpha \quad \text{and} \quad \alpha_{n+1} = G \, \alpha_n \Longrightarrow \{\alpha_n\} \to \alpha^1$$

$$\text{If } \alpha^1 < {\sf G} \, \alpha^1 \Longrightarrow \alpha^1_0 = {\sf G} \, \alpha^1 \quad \text{and} \quad \alpha^1_{n+1} = {\sf G} \, \alpha^1_n \\$$



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 $G : [\alpha, \beta] \rightarrow [\alpha, \beta]$  is defined as



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$$\mathcal{G}: [lpha, eta] 
ightarrow [lpha, eta]$$
 is defined as

Gv := maximal solution in  $[\alpha, \beta]$  of problem  $(P_v)$ 



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Discontinuous Case  ${\it G}:[\alpha,\beta] \rightarrow [\alpha,\beta]$  is defined as

Gv := maximal solution in  $[\alpha, \beta]$  of problem  $(P_v)$ 

 $(P_{\mathbf{v}}) \begin{cases} (\phi(u'(t)))' = f(t, \mathbf{v}, u(t), u'(t)) & \text{a. e. } t \in [0, T] \setminus P, \\ g_1(u(0), \mathbf{v}) = 0, \\ g_2(u(T), \mathbf{v}) = 0, \\ I_k(u(t_k), \mathbf{v}) = 0, \\ M_k(u(t_k^+), \mathbf{v}) = 0, \\ k = 1, \dots, p. \end{cases}$ 

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### Example Let A, B > 0, $\eta \in (0, 1)$ and $\xi \in (1, 2)$ be fixed.



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### Example Let $A, B > 0, \eta \in (0,1)$ and $\xi \in (1,2)$ be fixed.

Denoting by [x] the integer part of a real number x,



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#### Example Let A, B > 0, $\eta \in (0, 1)$ and $\xi \in (1, 2)$ be fixed.

Denoting by [x] the integer part of a real number x, let the following nonlinear impulsive boundary value problem



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Discontinuous Case Example Let A, B > 0,  $\eta \in (0, 1)$  and  $\xi \in (1, 2)$  be fixed. Denoting by [x] the integer part of a real number x, let the following nonlinear impulsive boundary value problem

$$\begin{cases}
u''(t) = F([u(\xi)]) | u'(t)|, & \text{ for all } t \in (0,2) \setminus \{1\}, \\
u(0) = A, \\
u(1) = u(\eta), \\
u^2(1^+) = u(\rho), \\
u(2) = B,
\end{cases}$$



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Discontinuous Case Example Let A, B > 0,  $\eta \in (0, 1)$  and  $\xi \in (1, 2)$  be fixed. Denoting by [x] the integer part of a real number x, let the following nonlinear impulsive boundary value problem

$$\mathsf{E} \begin{cases} u''(t) = F([u(\xi)]) | u'(t)|, & \text{ for all } t \in (0,2) \setminus \{1\}, \\ u(0) = A, \\ u(1) = u(\eta), \\ u^2(1^+) = u(\rho), \\ u(2) = B, \end{cases}$$

with  $F : \mathbb{R} \to \mathbb{R}$  defined as

$$F(x) = -\frac{x^3}{1+x^2}.$$



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#### We prove that this problem has exactly two positive solutions.



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Discontinuous Case We prove that this problem has exactly two positive solutions. The expressions of such solutions are given by

 $u_*(t) = u^*(t) = A$ , for all  $t \in [0,1]$ .



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$$u^*_*(t) = \sqrt{A} + (B - \sqrt{A})H(t, x^*_*), \quad ext{ for all } t \in (1, 2]$$



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$$u^*_*(t) = \sqrt{A} + (B - \sqrt{A})H(t, x^*_*), \quad \text{ for all } t \in (1, 2]$$

$$H(t,x) = \begin{cases} \frac{e^{-F([x])(t-1)} - 1}{e^{-F([x])} - 1} & \text{if } x \ge 1, \\ t - 1 & \text{if } 0 \le x < 1, \end{cases}$$

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 $x_*$  and  $x^*$  are the extremal solutions of equation

$$x = \sqrt{A} + (B - \sqrt{A})g([x]) \equiv \overline{G}(x),$$



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 $x_*$  and  $x^*$  are the extremal solutions of equation

$$x = \sqrt{A} + (B - \sqrt{A})g([x]) \equiv \bar{G}(x),$$

$$g(y) = \begin{cases} \frac{e^{-F(y)(\xi - 1)} - 1}{e^{-F(y)} - 1} & \text{for all } y > 0, \\ \xi - 1 & \text{if } y = 0. \end{cases}$$



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## **THANKS FOR YOUR ATTENTION!!**

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