

On Boundary Value Problems on an Infinite Interval for Higher Order Nonlinear Differential Systems

Ivan Kiguradze

A. Razmadze Mathematical Institute of I. Javakhishvili Tbilisi State University, Tbilisi, Georgia
E-mail: kig@rmi.ge

On an infinite interval $[a, +\infty[$, we consider the problem on the existence of a solution $(u_1, u_2) : [a, +\infty[\rightarrow \mathbb{R}^2$ of the differential system

$$u_1^{(m)} = f_1(t, u_2), \quad u_2^{(m)} = f_2(t, u_1), \quad (1)$$

satisfying the boundary conditions

$$\varphi_k(u_1^{(i-1)}(a), u_2^{(m-i)}(a)) = 0 \quad (k = 1, \dots, m), \quad \Phi_m(u_1, u_2) < +\infty, \quad (2)$$

where $f_i : [a, +\infty[\times \mathbb{R} \rightarrow \mathbb{R}$ ($i = 1, 2$) and $\varphi_k : \mathbb{R}^2 \rightarrow \mathbb{R}$ ($k = 1, \dots, m$) are continuous functions and

$$\Phi_m(u_1, u_2) = \int_a^{+\infty} (|u_1^{(m)}(t)u_2(t)| + |u_2^{(m)}(t)u_1(t)|) dt.$$

Analogous problems arise in the oscillation theory and in the case, where $f_1(t, x) \equiv x$, they have been studied in [1, 2]. In a general case, problem (1), (2) remains still unstudied. The results established by us fill to a certain extent the existing here gap.

We study the case in which the functions f_i ($i = 1, 2$) on the set $[a, +\infty[\times \mathbb{R}$ satisfy the inequalities

$$f_1(t, x)x \geq g_1(t, x), \quad (-1)^{m-1}f_2(t, x)x \geq g_2(t, x), \quad (3)$$

where $g_i : [a, +\infty[\times \mathbb{R} \rightarrow \mathbb{R}$ ($i = 1, 2$) are continuous functions such that

$$g_i(t, x) \leq g_i(t, y) \quad \text{for } t \geq a, \quad xy \geq 0, \quad |x| < |y| \quad (i = 1, 2),$$

$$\int_a^b |g_i(t, 0)| dt < +\infty \quad (i = 1, 2). \quad (4)$$

Along with (1), (2), we consider the auxiliary problem

$$u_1^{(m)} = (1 - \lambda)u_2 + \lambda f_1(t, u_2), \quad u_2^{(m)} = (-1)^{m-1}(1 - \lambda)u_1 + \lambda f_2(t, u_1), \quad (5)$$

$$(1 - \lambda)u_1^{(k-1)}(a) + \lambda \varphi(u_1^{(k-1)}(a), u_2^{(m-k)}(a)), \quad u_1^{(k-1)}(b) = 0 \quad (k = 1, \dots, m), \quad (6)$$

depending on the parameters $\lambda \in [0, 1]$ and $b \in]a, +\infty[$.

Proposition 1 (The principle of a priori boundedness). *Let there exist constants $b_0 > a$ and $r > 0$ such that for any $\lambda \in [0, 1]$ and $b \geq b_0$ every solution of problem (5), (6) admits the estimate*

$$\sum_{k=1}^m (|u_1^{(k-1)}(a)| + |u_2^{(k-1)}(a)|) + \Phi_m(u_1, u_2) \leq r.$$

Then problem (1), (2) has at least one solution.

Based on Proposition 1, the following theorem can be proved.

Theorem 1. *Let conditions (3), (4) be fulfilled, there exist mutually nonintersecting intervals $[a_{ik}, b_{ik}] \subset [a, +\infty[$ ($i = 1, 2; k = 1, \dots, m$) and a positive number r such that*

$$\lim_{|x| \rightarrow +\infty} \int_{a_{ik}}^{b_{ik}} g_i(t, x) dt = +\infty \quad (i = 1, 2; k = 1, \dots, m), \quad (7)$$

$$\varphi_k(x, y)x > 0 \quad \text{for } (-1)^{m-k+1}xy > r \quad (k = 1, \dots, m).$$

Then problem (1), (2) has at least one solution.

Particular cases of (2) are the boundary conditions

$$u_1^{(j_k-1)}(a) = \psi_k(u_2^{(m-j_k)}(a)) \quad (k = 1, \dots, m_0), \quad (8)$$

$$u_2^{(m-j_k)}(a) = \psi_k(u_1^{(j_k-1)}(a)) \quad (k = m_0 + 1, \dots, m), \quad \Phi_m(u_1, u_2) < +\infty;$$

$$u_1^{(k-1)}(a) = \psi_k(u_2^{(m-k)}(a)) \quad (k = 1, \dots, m), \quad \Phi_m(u_1, u_2) < +\infty, \quad (9)$$

and

$$u_2^{(m-k)}(a) = \psi_k(u_1^{(k-1)}(a)) \quad (k = 1, \dots, m), \quad \Phi_m(u_1, u_2) < +\infty, \quad (10)$$

where

$$m_0 \in \{1, \dots, m-1\}, \quad j_k \in \{1, \dots, m\}, \quad j_k \neq j_\ell \quad \text{for } k \neq \ell,$$

and $\psi_k : \mathbb{R} \rightarrow \mathbb{R}$ ($k = 1, \dots, m$) are continuous functions.

Corollary 1. *If along with (3), (4) and (7) the condition*

$$\liminf_{|x| \rightarrow +\infty} [(-1)^{m-j_k} \psi_k(x)x] > -\infty \quad (11)$$

is fulfilled, then problem (1), (8) has at least one solution.

Corollary 2. *If along with (3), (4) and (7) the condition*

$$\liminf_{|x| \rightarrow +\infty} [(-1)^{m-k} \psi_i(x)x] > -\infty \quad (k = 1, \dots, m) \quad (12)$$

is fulfilled, then problem (1), (9), as well as problem (1), (10) has at least one solution.

An interesting particular case of system (1) is the Emden–Fowler type differential system

$$u_1^{(m)} = p_1(t)|u_2|^{\lambda_1} \operatorname{sgn}(u_2) + q_1(t), \quad u_2^{(m)} = p_2(t)|u_1|^{\lambda_2} \operatorname{sgn}(u_1) + q_2(t), \quad (13)$$

where $\lambda_i > 0$ ($i = 1, 2$), and $p_i : [a, +\infty[\rightarrow \mathbb{R}$, $q_i : [a, +\infty[\rightarrow \mathbb{R}$ ($i = 1, 2$) are continuous functions.

Corollary 3. *Let*

$$p_1(t) \geq 0, \quad (-1)^{m-1}p_2(t) \geq 0 \quad \text{for } t \geq a,$$

$$|q_i(t)| \leq q_{i0}(t)|p_i(t)|^{\frac{1}{1+\lambda_i}} \quad \text{for } t \geq a \quad (i = 1, 2),$$

where $q_{i0} : [a, +\infty[\rightarrow [0, +\infty[$ ($i = 1, 2$) are continuous functions such that

$$\int_a^{+\infty} |q_{i0}(t)|^{1+\frac{1}{\lambda_i}} dt < +\infty \quad (i = 1, 2).$$

If, moreover, condition (12) holds, then problem (13), (9), as well as problem (13), (10) has at least one solution.

Consider now the case, where

$$\begin{aligned} f_i(t, 0) &= 0 \text{ for } t \geq a \quad (i = 1, 2), \\ f_1(t, x) &\leq f_1(t, y), \quad (-1)^{m-1} f_2(t, x) \leq (-1)^{m-1} f_2(t, y) \text{ for } t \geq a, \quad x < y. \end{aligned} \quad (14)$$

A nontrivial solution (u_1, u_2) of system (1) defined on some infinite interval $[a_0, +\infty[\subset [a, +\infty[$ is called:

- (i) **proper** if it is not identically equal to zero in any neighbourhood of $+\infty$;
- (ii) **oscillatory** if every its component changes sign in any neighbourhood of $+\infty$;
- (iii) **first kind singular solution** if there exists $t_0 > a_0$ such that $u_i(t) = 0$ for $t \geq t_0$ ($i = 1, 2$).

The problem on the existence of proper (in particular, oscillatory) solutions of system (1) is of special interest in the so-called “superlinear” case, when the right-hand sides of that system are the functions, rapidly growing with respect to the phase variables. Such are the cases that cover the results formulated below.

Corollary 4. *Let along with (12) and (14) the conditions*

$$f_i(t_i, x_0) \neq 0 \quad (i = 1, 2), \quad \sum_{k=1}^m |\psi_k(0)| > 0$$

be fulfilled, where $t_i > a$ ($k = 1, 2$) and $x_0 \neq 0$. If, moreover, system (1) has no first kind singular solution, then problems (1), (9) and (1), (10) are solvable, and their solutions are proper.

Theorem 2. *Let system (1) have no first kind singular solution and along with (12), (14) the condition*

$$\int_a^{+\infty} |f_i(t, x)| dt = +\infty \quad (i = 1, 2)$$

be fulfilled. Let, moreover, either

$$m \text{ be even and } \sum_{k=1}^m |\psi_k(0)| > 0,$$

or

$$m \geq 3 \text{ be odd, } \psi_m(x) \equiv 0, \quad \sum_{k=1}^{m-1} |\psi_k(0)| > 0.$$

Then problems (1), (9) and (1), (10) are solvable, and their solutions are oscillatory.

As an example, we consider the problem

$$u_1^{(m)} = p_1(t) \exp(h_1(t)|u_2|)|u_2|^{\lambda_1} \operatorname{sgn}(u_2), \quad u_2^{(m)} = p_2(t) \exp(h_2(t)|u_1|)|u_1|^{\lambda_2} \operatorname{sgn}(u_1), \quad (15)$$

$$u_1^{(k-1)}(a) = \alpha_k u^{(m-k)}(a) + c_k \quad (k = 1, \dots, m), \quad I_m(u_1, u_2) < +\infty, \quad (16)$$

where

$$\lambda_1 > 0, \quad \lambda_1 \lambda_2 \geq 1, \quad \alpha_k \in \mathbb{R} \quad (i = 1, \dots, m),$$

and $p_i, h_i : [a, +\infty[\rightarrow \mathbb{R}$ ($i = 1, 2$) are continuous functions such that

$$p_1(t) \geq 0, \quad (-1)^{m-1} p_2(t) \geq 0, \quad h_1(t) \geq 0, \quad h_2(t) \geq 0 \text{ for } t \geq a.$$

From Theorem 2 it follows

Corollary 5. *Let*

$$\int_a^{+\infty} p_i(t) \exp(xh_i(t)) dt = +\infty \text{ for } x > 0 \text{ (} i = 1, 2)$$

and let, moreover, either

$$m \text{ be even, } (-1)^{m-k} \alpha_k > 0 \text{ (} k = 1, \dots, m), \sum_{k=1}^m |c_k| > 0,$$

or

$$m \text{ be odd, } (-1)^{m-k} \alpha_k > 0 \text{ (} k = 1, \dots, m-1), \alpha_m = c_m = 0, \sum_{k=1}^{m-1} |c_k| > 0.$$

Then problem (15), (16) is solvable and every its solution is oscillatory.

References

- [1] I. T. Kiguradze, A boundary value problem with a condition at infinity for higher-order ordinary differential equations. (Russian) *Partial differential equations and their applications (Russian) (Tbilisi, 1982)*, 91–105, 249–250, *Tbilis. Gos. Univ., Tbilisi*, 1986.
- [2] I. Kiguradze and T. Chanturia, *Asymptotic properties of solutions of nonautonomous ordinary differential equations. Springer Science & Business Media*, 2012.